# Relativistic Zel'dovich approximation and its applications 

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## General setting

- matter model: dust - no pressure
- $3+1$ foliation
- synchronous gauge - no rotation
- Einstein-de Sitter background - no $\Lambda$
- we will use the principal scalar invariants of extrinsic curvature $K_{i j}$ I, II, III and
- standard kinematical decomposition into: expansion rate $\Theta=-K_{k}^{k}$ and shear $\sigma^{i}{ }_{j}=-K^{i}{ }_{j}-\frac{1}{3} \Theta \delta^{i}{ }_{j}$
- Buchert equations - solvable for special cases; Buchert equations + RZA -solvable for generic fields


## Euler-Newton system

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$$
\begin{aligned}
& \partial_{t} \vec{v}=-(\vec{v} \cdot \nabla) \vec{v}+\vec{g} \\
& \partial_{t} \varrho=-\nabla \cdot(\varrho \vec{v}) \\
& \nabla \times \vec{g}=\overrightarrow{0} \\
& \nabla \cdot \vec{g}=-4 \pi G \varrho
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$$

- We introduce the trajectory field $\vec{f}(\vec{X}, t)$ and the Jacobian $J=\frac{1}{6} \epsilon_{i j k} \epsilon^{l m n} f^{i}{ }_{\mid l} f^{j}{ }_{\mid m} f^{k}{ }_{\mid n}$ and implicitly solve the evolution equations by:

$$
\vec{v}=\dot{\vec{f}} ; \vec{g}=\ddot{\vec{f}} ; \varrho=\frac{\varrho}{J}, \quad J>0
$$

## Lagrange-Newton system

- We define the functional determinant of three functions $A, B, C$ :

$$
\mathcal{J}(A, B, C):=\frac{\partial(A, B, C)}{\partial\left(X_{1}, X_{2}, X_{3}\right)}=\epsilon_{i j k} A_{\mid i} B_{\mid j} C_{\mid k}
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$$

- The Lagrange-Newton System (LNS) takes the form:

$$
\begin{aligned}
& \mathcal{J}\left(\ddot{f}^{i}, f^{i}, f^{k}\right)=0 \\
& \mathcal{J}\left(\ddot{f}^{1}, f^{2}, f^{3}\right)+\text { cycl. }=-4 \pi G \varrho
\end{aligned}
$$

- This is equivalent to ENS provided that the trajectory field is unique and the Jacobian is greater than 0


## First order scheme

- We decompose $\vec{f}$ into a homogeneous and isotropic background deformation $\vec{f}_{H}(\vec{X}, t)=a(t) \vec{X}$ and an inhomogeneous deformation field $\vec{p}(\vec{X}, t)$

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\vec{f}(\vec{X}, t)=a(t) \vec{X}+\vec{p}(\vec{X}, t)
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- We introduce rescaled quantities $\vec{q}=\vec{F}(\vec{X}, t) \equiv \vec{f}(\vec{X}, t) / a(t)$ and $\vec{P}(\vec{X}, t) \equiv \vec{p}(\vec{X}, t) / a(t)$


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- First-order equations for the inhomogeneous part are:

$$
\begin{aligned}
& a^{2} \nabla_{0} \times \ddot{\vec{p}}-\ddot{a} a \nabla_{0} \times \vec{p}=\overrightarrow{0} \\
& a^{2} \nabla_{0} \cdot \ddot{\vec{p}}+(2 \ddot{a} a) \nabla_{0} \cdot \vec{p}-4 \pi G\left(\varrho\left(\varrho_{\varrho_{H}}\right)\right.
\end{aligned}
$$

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& \ddot{\vec{P}}^{T}+2 H \dot{\vec{P}}^{T}=\overrightarrow{0} \\
& \ddot{\vec{P}}^{L}+2 H \dot{\vec{P}}^{L}-4 \pi G \varrho_{H} \vec{P}^{L}=\frac{1}{a^{3}} \vec{W}(\vec{X})
\end{aligned}
$$

where $\vec{W}(\vec{X}) \equiv \ddot{\vec{P}}^{L}\left(\vec{X}, t_{0}\right)+2 H\left(t_{0}\right) \dot{\vec{P}}^{L}\left(\vec{X}, t_{0}\right)$ is the initial peculiar-acceleration field.

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- Special case of first-order solution - Zel'dovich approximation:

$$
\vec{u}(\vec{X}, t)=\vec{w}(\vec{X}, t) t ; \quad t=t_{0}
$$

where

$$
\vec{u}=a \dot{\vec{P}}, \quad \text { and } \quad \vec{w}=\dot{\vec{u}}+H \vec{u}=2 \dot{a} \dot{\vec{P}}+a \ddot{\vec{P}}
$$

## Basic scheme

- We employ the ADM equations and express them with a single variable i.e. the cartan co-frame $\eta_{i}^{a}$ (M.Kasai, PRD 52, 5605 (1995); T.Buchert and M. Ostermann, PRD 86, 023520 (2012) arXiv:1203.6263


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- We derive the general first order solutions for the dynamical variable
- We use the perturbed deformation to functionally evaluate the quantities of interest e.g. density, curvature


## Lagrange-Einstein system

- Lagrange-Einstein System in ADM formulation

$$
\begin{aligned}
& \delta_{a b} \ddot{\eta}^{a}{ }_{[i} \eta^{b}{ }_{j]}=0 \\
& \frac{1}{2} \epsilon_{a b c} \epsilon^{i k l} \ddot{\eta}_{i}{ }_{i} \eta^{b}{ }_{k} \eta^{c}{ }_{l}=\Lambda J-4 \pi G J{ }_{\varrho}^{\circ} \\
& \left(\epsilon_{a b c} \epsilon^{i k l} \dot{\eta}^{a}{ }_{j} \eta^{b}{ }_{k} \eta^{c}{ }_{l}\right)_{\| i}=\left(\epsilon_{a b c} \epsilon^{i k l} \dot{\eta}_{i} \eta^{b}{ }_{k} \eta^{c}{ }_{l}\right)_{\| j} \\
& \epsilon_{a b c} \epsilon^{m k l} \dot{\eta}^{a}{ }_{m} \dot{\eta}^{b}{ }_{k} \eta^{c}{ }_{l}=16 \pi G J \stackrel{\circ}{\varrho}-J R \\
& \frac{1}{2}\left(\epsilon_{a b c} \epsilon^{i k l} \ddot{\eta}^{a}{ }_{j} \eta^{b}{ }_{k} \eta^{c}{ }_{l}-\frac{1}{3} \epsilon_{a b c} \epsilon^{m k l} \ddot{\eta}^{a}{ }_{m} \eta^{b}{ }_{k} \eta^{c}{ }_{l} \delta^{i}{ }_{j}\right) \\
& +\left(\epsilon_{a b c} \epsilon^{i k l} \dot{\eta}^{a}{ }_{j} \dot{\eta}^{b}{ }_{k} \eta^{c}{ }_{l}-\frac{1}{3} \epsilon_{a b c} \epsilon^{m k l} \dot{\eta}^{a}{ }_{m} \dot{\eta}^{b}{ }_{k} \eta^{c}{ }_{l} \delta^{i}{ }_{j}\right) \\
& =-J \tau_{j}^{i}
\end{aligned}
$$

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$$
\ddot{P}+3 H \dot{P}=\frac{1}{a^{2}}\left(\ddot{P}\left(t_{0}\right)+3 H\left(t_{0}\right) \dot{P}\left(t_{0}\right)\right)
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& \ddot{P}+3 H \dot{P}=\frac{1}{a^{2}}\left(\ddot{P}\left(t_{0}\right)+3 H\left(t_{0}\right) \dot{P}\left(t_{0}\right)\right) \\
& \ddot{\Pi}_{j}^{i}+3 H \dot{\Pi}_{j}^{i}=-{ }^{(1)} \tau_{j}^{i}
\end{aligned}
$$

where $\Pi^{i}{ }_{j} \equiv P^{i}{ }_{j}-\frac{1}{3} P \delta^{i}{ }_{j}$.

## General first-order solution

- We separate the time and spatial derivatives and make the ansatz

$$
P_{i}^{a}(X, t)={ }^{0} Q^{a}{ }_{i}(X)+q_{1}(t)^{1} Q^{a}{ }_{i}(X)+q_{2}(t)^{2} Q^{a}{ }_{i}(X)
$$

where the time functions $q_{1 / 2}(t)$ are the two solutions of:

$$
\ddot{q}+2 \frac{\dot{a}}{a} \dot{q}+\left(3 \frac{\ddot{a}}{a}-\Lambda\right)\left(q+q\left(t_{0}\right)\right)=0 .
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$$

- With the ansatz and its time derivatives we find

$$
\begin{aligned}
{ }^{1} Q_{i}^{a} & =+\frac{\dot{q}_{2}\left(t_{0}\right) \ddot{P}_{i}^{a}\left(t_{0}\right)-\ddot{q}_{2}\left(t_{0}\right) \dot{P}_{i}^{a}\left(t_{0}\right)}{\ddot{q}_{1}\left(t_{0}\right) \dot{q}_{2}\left(t_{0}\right)-\dot{q}_{1}\left(t_{0}\right) \ddot{q}_{2}\left(t_{0}\right)}, \\
{ }^{2} Q_{i}^{a} & =-\frac{\dot{q}_{1}\left(t_{0}\right) \ddot{P}_{i}^{a}\left(t_{0}\right)-\ddot{q}_{1}\left(t_{0}\right) \dot{P}_{i}^{a}\left(t_{0}\right)}{\ddot{q}_{1}\left(t_{0}\right) \dot{q}_{2}\left(t_{0}\right)-\dot{q}_{1}\left(t_{0}\right) \ddot{q}_{2}\left(t_{0}\right)}
\end{aligned}
$$

- ... together with

$$
{ }^{0} Q^{a}{ }_{i}=P_{i}^{a}\left(t_{0}\right)-q_{1}\left(t_{0}\right)^{1} Q^{a}{ }_{i}-q_{2}\left(t_{0}\right)^{2} Q^{a}{ }_{i}
$$

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$$

- Finally we obtain an expression for the first-order peculiar coframe:

$$
{ }^{(1)} \tilde{\eta}^{a}{ }_{i}=\stackrel{~}{\eta}^{a}{ }_{i}+\left(q_{1}(t)-q_{1}\left(t_{0}\right)\right)^{1} Q^{a}{ }_{i}+\left(q_{2}(t)-q_{2}\left(t_{0}\right)\right)^{2} Q^{a}{ }_{i}
$$

where $\stackrel{\eta}{\eta}^{a}{ }_{i} \equiv \delta^{a}{ }_{i}+P^{a}{ }_{i}\left(t_{0}\right)$ is the coframe at the initial time.

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where $\stackrel{\eta}{\eta}^{a}{ }_{i} \equiv \delta^{a}{ }_{i}+P^{a}{ }_{i}\left(t_{0}\right)$ is the coframe at the initial time.

- Additionally, we define some useful peculiar-quantities $u^{a}{ }_{i}$ and $w^{a}{ }_{i}$ :

$$
\begin{aligned}
& \dot{\eta}_{i}^{a}=H \eta^{a}{ }_{i}+u^{a}{ }_{i}, \quad u^{a}{ }_{i} \equiv a \dot{P}_{i}^{a} \\
& \ddot{\eta}_{i}^{a}=\frac{\ddot{a}}{a} \eta^{a}{ }_{i}+w^{a}{ }_{i}, \quad w^{a}{ }_{i} \equiv a \ddot{P}_{i}^{a}+2 \dot{a} \dot{P}_{i}^{a}
\end{aligned}
$$

## Relativistic Zel'dovich Approximation

- In analogy to the Newtonian investigation we restrict ourselves to the trace part and we impose the following slaving conditions:

$$
{ }^{2} Q^{a}{ }_{i}(X)=0 \quad w_{i}^{a}=\left(2 H+\frac{\ddot{q}_{1}}{\dot{q}_{1}}\right) u_{i}^{a}
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$$

resulting in:

$$
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$$

- Thus, we obtain the expression for the peculiar coframe:

$$
\begin{array}{r}
\text { RZA } \tilde{\eta}_{i}^{a}(X, t)=\delta_{i}^{a}+P_{i}^{a}\left(X, t_{0}\right)+\xi(t) \dot{P}_{i}^{a}\left(X, t_{0}\right) \\
\xi(t) \equiv\left(q_{1}(t)-q_{1}\left(t_{0}\right)\right) / \dot{q}_{1}\left(t_{0}\right)
\end{array}
$$

## Averaged equations I

- We define the domain dependent scale factor

$$
a_{\mathcal{D}}(t):=\left(\frac{V_{\mathcal{D}}(t)}{V_{\mathcal{D}_{\mathbf{i}}}}\right)^{1 / 3}
$$

where the volume of the domain is given by:

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V_{\mathcal{D}}(t):=\int_{\mathcal{D}} \mathrm{d} \mu_{\mathrm{g}}
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$$
V_{\mathcal{D}}(t):=\int_{\mathcal{D}} \mathrm{d} \mu_{\mathrm{g}}
$$

- We apply the following commutation rule to the Raychaudhuri and Hamilton equations

$$
\partial_{t}\left\langle\Psi\left(t, X^{k}\right)\right\rangle_{\mathcal{D}}-\left\langle\partial_{t} \Psi\left(t, X^{k}\right)\right\rangle_{\mathcal{D}}=\langle\Theta \Psi\rangle_{\mathcal{D}}-\langle\Theta\rangle_{\mathcal{D}}\langle\Psi\rangle_{\mathcal{D}}
$$

- We obtain the generalised Friedmann equations for inhomogeneous fluids:
$\rightarrow$ the averaged Raychaudhuri equation:

$$
3 \frac{\ddot{a}_{\mathcal{D}}}{a_{\mathcal{D}}}+4 \pi G \frac{M_{\mathcal{D}_{\mathbf{i}}}}{V_{\mathcal{D}_{\mathbf{i}}} a_{\mathcal{D}}^{3}}=\mathcal{Q}_{\mathcal{D}}
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$$

$\rightarrow$ the averaged Hamiltonian constraint

$$
\left(\frac{\dot{a}_{\mathcal{D}}}{a_{\mathcal{D}}}\right)^{2}-\frac{8 \pi G}{3} \frac{M_{\mathcal{D}_{\mathrm{i}}}}{V_{\mathcal{D}_{\mathrm{i}}} a_{\mathcal{D}}^{3}}+\frac{\langle\mathcal{R}\rangle_{\mathcal{D}}}{6}=-\frac{\mathcal{Q}_{\mathcal{D}}}{6},
$$

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\left(\frac{\dot{a}_{\mathcal{D}}}{a_{\mathcal{D}}}\right)^{2}-\frac{8 \pi G}{3} \frac{M_{\mathcal{D}_{\mathrm{i}}}}{V_{\mathcal{D}_{\mathrm{i}}} a_{\mathcal{D}}^{3}}+\frac{\langle\mathcal{R}\rangle_{\mathcal{D}}}{6}=-\frac{\mathcal{Q}_{\mathcal{D}}}{6}
$$

where the kinematical backreaction term is given by:

$$
\mathcal{Q}_{\mathcal{D}}=2\langle\mathrm{II}\rangle_{\mathcal{D}}-\frac{2}{3}\langle\mathrm{I}\rangle_{\mathcal{D}}^{2}=\frac{2}{3}\left\langle\left(\Theta-\langle\Theta\rangle_{\mathcal{D}}\right)^{2}\right\rangle_{\mathcal{D}}-2\left\langle\sigma^{2}\right\rangle_{\mathcal{D}}
$$

## Kinematical backreaction

With the perturbed co-frame ${ }^{\text {RZA }} \tilde{\eta}^{a}{ }_{i}(X, t)=\delta^{a}{ }_{i}+P^{a}{ }_{i}\left(X, t_{0}\right)+\xi(t) \dot{P}^{a}{ }_{i}\left(X, t_{0}\right)$ the backreaction takes the form (T.Buchert et al., PRD 87, 123503 (2013), arXiv: 1303.6193):

$$
{ }^{\text {RZA }} \mathcal{Q}_{\mathcal{D}}=\frac{\dot{\xi}^{2}\left(\gamma_{1}+\xi \gamma_{2}+\xi^{2} \gamma_{3}\right)}{\left(1+\xi\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}}+\xi^{2}\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}+\xi^{3}\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}}\right)^{2}}
$$

with:
(1) $\quad \gamma_{1}:=2\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}-\frac{2}{3}\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}}^{2}$
(2) $\quad \gamma_{2}:=6\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}}-\frac{2}{3}\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}}$
(3) $\quad \gamma_{3}:=2\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}}\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}}-\frac{2}{3}\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}^{2}$

## Intrinsic curvature

$$
{ }^{\text {RZA }} \mathcal{R}_{\mathcal{D}}=\frac{\dot{\xi}^{2}\left(\tilde{\gamma}_{1}+\xi \tilde{\gamma}_{2}+\xi^{2} \tilde{\gamma}_{3}\right)}{1+\xi\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}}+\xi^{2}\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}+\xi^{3}\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}}}
$$

with:

$$
\begin{aligned}
& \tilde{\gamma}_{1}=-2\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}}-12\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{H}{\dot{\xi}}-4\left\langle\mathrm{I}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{\ddot{\xi}}{\dot{\xi}^{2}} \\
& \tilde{\gamma}_{2}=-6\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}}-24\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{H}{\dot{\xi}}-8\left\langle\mathrm{II}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{\ddot{\xi}}{\dot{\xi}^{2}} \\
& \tilde{\gamma}_{3}=-36\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{H}{\dot{\xi}}-12\left\langle\mathrm{III}_{\mathbf{i}}\right\rangle_{\mathcal{I}} \frac{\ddot{\xi}}{\dot{\xi}^{2}}
\end{aligned}
$$

## Scale factors, expansion rates

Examples of the intrinsic curvature effects on scale factor and expansion rate of collapsing domain


## General setting

## Euler-Newton system

 Lagrange-Newton system First order scheme
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General first-order solution

Relativistic Zel'dovich Approximation
Averaged equations I
Kinematical backreaction
Intrinsic curvature Scale factors, expansion rates
On the Green and Wald formalism Brief history of the debate on Green and Wald formalism Assumptions (Following arXiv:1011.4920v2 [gr-qc])
Weak limit, Green and Wald equations
Green and Wald

## On the Green and Wald formalism

## Brief history of the debate on Green and Wald formalism

- Ishibashi and Wald: 'Can the Acceleration of Our Universe Be Explained by the Effects of Inhomogeneities?'(arXiv:gr-qc/0509108) - negligible backreaction


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## Assumptions (Following arXiv:1011.4920v2 [gr-qc])

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where:
$t_{a b}(\lambda)=2 \nabla_{[a} C_{e] b}^{e}-2 C^{f}{ }_{b[a} C_{e] f}^{e}-g_{a b}(\lambda) g^{c d}(\lambda) \nabla_{[c} C_{e] d}^{e}+g_{a b}(\lambda) g^{c d}(\lambda) C^{f}{ }_{d[c} C_{e] f}^{e}$, and

$$
C_{a b}^{c}=\frac{1}{2} g^{c d}(\lambda)\left\{\nabla_{a} g_{b d}(\lambda)+\nabla_{b} g_{a d}(\lambda)-\nabla_{d} g_{a b}(\lambda)\right\}
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$\rightarrow \quad t_{a b}^{(0)}$ obeys the weak energy condition i.e. $t_{a b}^{(0)} t^{a} t^{b} \geq 0$
- To put it in words: $t_{a b}^{(0)}$ can not mimic the dark energy.


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## Problems with interpretation

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Example of density profile


- $\quad \mathrm{w}-\lim T_{a b}(\lambda)=T_{a b}^{(0)}$ ? - averaging over inhomogeneities that were not originally there


## Further reading

For further details see: Is there proof that backreaction of inhomogeneities is irrelevant in cosmology? by T. Buchert et al. (arXiv:1505.07800[gr-qc])

## Summary

- RZA provides a potentially powerful tool for describing the large scale structure of the Universe
- Intrinsic curvature plays a role in the evolution of the scale factor
- Small metric perturbations may cause significant curvature deviations and thus deviate from the homogeneous model
- The 'inhomog' code will provide a tool for RZA calculations

